

Review of VANET Mobility Models with New Cluster Based Routing Protocol

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Abstract-As we know that MANET and vehicle technology is growing and hence becoming the emerging field for most of researchers. Recently, new routing protocol proposed by some authors in order to overcome the problem of discovering and maintaining the efficient and effective route for the data transmission over the wireless network. At first stage of this research we are presenting investigation of that new approach of routing called cluster based routing for VANET and compare their performances with existing routing protocols. This new routing approach having aim of increasing the overall network throughput, minimize end to end delay. In this review paper we are aiming to take survey of cluster based new routing protocol for VANET, survey of mobility models used, and finally the comparative analysis of different existing VANET routing protocols.

Keywords: VANET, Road based routing, reactive routing protocols, proactive routing protocols, broadcasting based protocols, cluster based routing protocols

I. INTRODUCTION

Vehicular networks (VANET) attract a lot of attention in the research world. IPv6 support is needed in vehicular ad hoc network (VANET) with geographical routing. Geographic routing in vehicular ad hoc network (VANET) is becoming an interesting topic to deliver safety messages between cars but also between a car and a roadside infrastructure within a designated destination area. Static and dynamic cluster heads are dependable for synchronization between the nodes inside their clusters, and between the clusters [1]. Periodic re-clustering can choose nodes with longer journey occasion and extra number of stops similar to buses act as cluster heads. Network lifetime is extended through (i) choosing the best pathway with smallest intrusion of nodes, (ii) periodic updating in cluster head about the routing and cluster information's, and (iii) routing from side to side the nodes with normal velocity of nodes. In this job, we present a separate cluster based approach that considers a hybrid and dynamic mobility model. Based on this approach, we present a Location based Multipath Flooding algorithm, which have three prime goals: (i) reducing delay, (ii) prolonging network lifetime by 2-hop cache, and (iii) maximal data delivery ratio at high mobility [2] [3].

Clustering was planned as a helpful device for locating the destinations. The difficulty that we address has sole necessities that differentiate it from the energy based load-balancing difficulty in distributed systems. Real-time communication protocols are inappropriate in an urban

mobility model, since we will not develop any normal and monotonous scenarios. In a total scattered system like VANET, each node can do something as a resource or a spread node, which motivates they require for resourceful algorithms to choose servers according to the outlined system goals. Every vehicle must stores the information interrelated to the cluster inside the broadcast variety of source node. In our model, a fixed number of dynamic and static sources are recognized to each vehicle of the organization, and a static source is eternally accessible for processing huge quantity of data [4]. Receiver-oriented approach has been planned where numerous nodes can decide to retransmit the message, leading to collisions and/or bandwidth wastage. Every node waits for a random delay before sending the message, except if a neighbor already present. At elevated mobility situation every nodes shift fast and it's extremely hard to calculate the positions through the source. Because of extremely dynamic neighbors this process is not appropriate for transmitting emergency/alert messages. In our integrated approach the information pertaining to travel is maintained in both sources, smaller time in dynamic source and longer period in static sources for upcoming purpose. If the space between two cluster head nodes is found to be a smaller amount than the threshold, the cluster with fewer members is dismissed to decrease communication overheads and its members join other clusters. During high mobility situation the procedure of reclustering increases the communication rate. Locating the place of nodes, relative rate predictions and effective communication distance among nodes according to mobility are dealt in our approach [5].

In addition, we integrate cluster based routing in a diversity of models such as Random Waypoint, RPGM and Manhattan models and evaluate with our new approach. Our results demonstrate that the routing presentation may be different considerably across diverse mobility models and presentation of the protocols may differ with diverse scenarios. This result can be explained by the boundary of the mobility characteristics with the spatial and chronological dependencies. Grouping the vehicles can be differentiated in diverse mobility models according to their spatial and chronological dependencies. VANET's are characterized by high mobility communication in infrastructure-less environments and dynamic topology situations, which lead to normal network partition. VANET's dependence on outside parameters like type of the roads, driver's decision, timing, weekdays, and speed of the vehicle and location of the vehicles make it difficult to monitor and manage the whole network. Mobility aware

ripple free clusters are used for maintaining steady vehicular infrastructure and inter cluster routing. Therefore network can adaptively regulate its dominant routing method based on its mobility features [6]. Our clustering scheme works well in a dynamic atmosphere because it does not need frozen period of motion for initial cluster configuration. Therefore it is more suitable for urban environments where vehicles change their speed and direction normally. Vehicular networks are frequently deployed by the constraint of roadways where trees and buildings control the practical transmissions as compared to open fields [7]. Vehicle nodes with low relative rate are assigned to the same cluster to tighten the association in such a cluster [8].

As in this research work we are about to present the investigation work over clustering approach for routing of VANET networks for more efficient performance. Hence it is more suitable for urban environments where vehicles change their speed and direction frequently. Vehicular networks are often deployed by the constraint of roadways where trees and buildings influence the practical transmissions as compared to open fields. Vehicle nodes with low relative speed are assigned to the same cluster to tighten the connection in such a cluster. In below section II we are first presenting the investigation study of cluster based routing protocol, after that in section III review of new cluster based routing algorithms discussed, in section IV review of mobility models presented, finally in section V we are presenting the comparative study of VANET routing protocols in brief.

II. INVESTIGATION OF CLUSTER BASED ROUTING

The features of static and dynamic clustering are combines mutually to build Cluster based Routing. Static sources situated at the street signals are used to outline static clusters. Static Cluster head is too recognized as Street corners and congested places [3] [4].

In this cluster based approach buses are selected as dynamic sources. These buses are having the predefined path and time graph. The predefined path and time graph to grip the elevated mobility situations known as dynamic cluster head. Hierarchical clustering creates layering surroundings. That layering surroundings contains some of the major challenges in such ad hoc networks. Top layer completed up of static cluster head, middle layer completed up of dynamic cluster head and lower layer consists of ordinary vehicles. Network topology also changes since of highly dynamic vehicles. This in turn affects the presentation of the network. Then it may also appeal to protocol mechanisms to act in response to such dynamics. Malfunctions in routing are responded by using Mobility alertness in topology. For cluster structure there are some mobility metrics in categorize to form a constant cluster structure thereby decreasing its influence on cluster topology. Structural design of the cluster is determined by using the Vehicles Mobility performance. Vehicles are differentiated in two dissimilar ways whichever by those vehicles which are in the communication ranges of dynamic sources or else by those vehicles which are in the ranges of static sources mounted at traffic signals and road

junctions. By differentiating vehicles into group so, the re-affiliation and re-clustering rate can be logically decreased. Based on the following parameters (VID, LID, s, VLT) we defined in Algorithm 1 dynamic clustering attempts to partition a number of nodes into multi-hop clusters. The each vehicle node in a cluster has its individual distinctive VID and Location ID representing the road in an exacting area of the city it belongs. The symbol 's' indicates the rate of the vehicle and VLT indicates the vehicles life time in an exacting cluster over some time with the probability of p, D despite of the hop distance between them. The main purpose is to support robust and well-organized routing, and adaptively regulate and execute its dominant routing scheme depending on the network mobility manner.

In dynamic clustering scheme, clustering scheme requires no periodic re-clustering. When a vehicle enters into the clustering zone its sole VID is registered into the cluster head and becomes a part of that cluster. By sending out CJReq message any unclustered vehicle joins a cluster. The dimension of the cluster may be affected by Mobility, low mobility increases the size of the cluster compared to high mobility, leading to increase in the number of clusters. A Vehicle having a convincing VID can link the cluster and its speed is also a significant characteristics, if any further new vehicle other than ambulance or rescue vehicle enters into the cluster with more than an average rate then it is not necessary to renew it all over the place. Behind a convinced period of time if a vehicle does not take delivery of a response message, it will creates a fresh cluster for that vehicle and it will become the start for itself, even behind that it will send and receive message to turn out to be a cluster member or it will carry on as a cluster head [6] [7].

In the current case, every vehicle separately runs clustering and routing scheme with no any backing of other neighboring members. Therefore, accuracy is maintained still during high mobility. Each vehicle broadcasts organize messages once entering into the cluster region.

The algorithm CJM (Cluster Join Messages) is appropriate for a network with high mobility for cluster construction, where mobility of vehicles affects the cluster topology. Cluster configuration is only depends on CJM and not by any other messages so expenses are avoided; similar to the thought proposed in [10]. Before passing the data the vehicle enters into a cluster region it periodically broadcasts CCM (Cluster Connect Messages), As soon as it receives the response it will start data transmission.

This cluster based routing approach ripple outcome of re-clustering is decreased by choosing recognized and defined vehicles like buses as cluster heads and this effect has been decreased in some places by mounting static cluster heads, therefore with no any force alternations cluster structure and topology has to be maintained smoothly. One benefit of Static cluster head is gathering correct neighbor information and cluster structure is promised with explicit attributes. One more metric is the period of each vehicle to become an associate of the cluster. By sending a message to all neighbors (n), each vehicle can help each of its neighbors to choose the distance among them. Then each neighbor should send

reply information(r), including the VID, CID, distance, speed and Direction. Hence, for cluster formation each vehicle needs to send out (n+r) messages.

Throughout cluster building phase, should think how to reduce the amount of clustering-related communication exchanged for the cluster formation. From time to time every unclustered vehicle seeks a cluster to connection behind transfer CJM messages infrequently, and creates a single node cluster to cover itself when there is no right cluster to join. A too-small cluster, while, may create vast number of clusters and thus increase the distance end to end of hierarchical routes, substantial in longer end-to-end stoppage. To maintain away from this, two clusters are integrated based on cluster head speed and by choosing slow rate cluster head as new head [9]. In our no overlapping multihop structure, data communication is stretchier and do not have a skip limit between two neighboring cluster heads.

III. REVIEW OF NEW VANET ALGORITHMS

Here the first algorithm which is related to the multipath flooding case for VANET is presented below:

Algorithm 1: Location based Multipath Flooding

Parameters

CJReq –Cluster Join Request
CJRep –Cluster Join Reply *CJReq* (*SVID*, *IMVID*, *DVID*, *VC*)
CJRep (*DVID*, *IMIID*, *SVID*, *VC*)
CVID-Current Vehicle ID
DV-Destination Vehicle
DVID-Destination Vehicle ID
IMVID-Intermediate Vehicle ID
NV-Number of Vehicles
NVID-Neighbor Vehicle ID
SP-Shortest Path
SVID-Source Vehicle ID
VC- Vehicle counter
VID-Vehicle ID
VD-Vehicle Distance
 At Source
 a) flood (*CJReq*) all Immediate Neighbors (*NVID*)
 b) *VC* = # (*NV*)
 for each relay node
 {
 for each *CJReq* received
 {
 if new *NVID* = old *NVID*
 drop (*RREQ*) to avoid repetition
 if (current node(*CVID* = *DVID*)
 then *DVID* is set to nodes id
 else
 {
 i) *CJReq* to *IMVID* add(*CVID*)
 ii) Find *VC1* = # (*NV*)
 }
 }
 At Destination
 For each *CJReq* received, send (*CJRep*) to source
 If (*speed* > *thresholdspeed*)

```

update only VID in Cluster head
else
sort(CJRep IMVID)
update details of vehicle to all nodes
At source {
till(timestamp < threshold time)
{
link = SORT(CJRep IMVID)
for each link
{
find SP = MIN(CJRep VC)
send (data) to DV through SP
}
SORT(CJRep IMVID)
for each IMVID in CJRRep
{
calculate VD
SORT( IMVID) in ascending order of VD
calculate SP # elements whose VD
store all VID in an array in each cluster
}

```

The VANET research is deception on the progress of vehicular to vehicular announcement system that enables suitable, stable and the inexpensive allotment of data for the safety and for the console on the Road. The Dynamic topologies containing highly dynamic nodes will be the reason the collision on wireless medium. Therefore packet delays and losses occur frequently. Each node of VANET acts as a router to transmit the message during the network. Consequently, VANET must be a scattered multi-hop network with a time varying

In a variety of phases such as design phase, the cluster formation phase, link establishment phase, data transmission phase and traffic Control phase. VANET research had focused on the development of a variety of routing protocols, analysis of these approaches under the various mobility models, and attempts to managing the mobility-related routing issues. The efficiency of the Channel can be increased by reduces the security overhead. The Unsecured network is more dangerous than an overloaded network. Since that the disaster can be avoided within the fractions of a second and the reducing the alert messages delivery delay is another one priority. We are trying to decrease the redundancy to avoid the message delay and exploit the bandwidth efficiently. Our aim is that to provide instant information about a crash to other vehicles. Only the cluster-head vehicles need to send the consolidated safety messages over a channel. It will share out vague indication of the events that occur during traffic collisions leading to the understanding of the relations processes. Unconsciousness provides safety driving information and drivers can decide on which alternative path to choose before entering into the critical region of the cluster. It prevents further accidents, traffic congestion and finally saves lives and time.

Algorithm 2: Cluster Based Routing (CBR)

Parameters

```

CID - Cluster ID
CH - Cluster Head
ns - Source Node
nd - Destination Node
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ni - Intermediate Node
tpath - Temporary Path
DU-Data Update
For a new vehicle
if valid CID
receive past information
and
make entry into the list
register its CID in existing CH
choose the CH
new vehicle is either source or relay node
if source calculate speed
if CID speed < old CH speed
assign(new vehicle=CH)
start flood(ns,nd,tpath)
Upon receiving flood(ns,nd,tpath) from source
Check if (ni==nd) and
if ( tpath length > best path )
{ set newpath =tpath
send newroute(nd,ns,newpath) }
end if
if no RouteReq then
wait until threshold time
endif
if any RouteRep received
find # of (interference nodes)
choose minpath(interference nodes)
endif
else
flood (RouteReq)
until new route
{
hold existing route information upto threshold
time t
receiving flood(ns,nd,tpath) from neighbor node
if (ni= source)
{
store the path information
forward(data)
}
else
{ forward newroute(nd,ns,path)
}
end if
end if
    
```

IV. REVIEW OF MOBILITY MODEL

With the new approach of clustering, one new thing which we want to add in this research is Hybrid mobility model

combines which more than a few existing mobility models together. We observed that this model is very much helpful for VANET networks. Mobility creates very dynamic surroundings that pose some of the main challenges in such ad hoc networks. The relative movement among nodes creates or breaks relations and changing the network topology. This in turn affects the presentation of the network and also invokes protocol mechanisms to act in response to such dynamics. Hence, mobility modeling becomes essential to the evaluation and learns of ad hoc networking protocols. Traditional mobility models, random walk, random waypoint, Manhattan model, gauss markov and reference point group mobility model attempt to mimic the movements of vehicle nodes.

V. VANET ROUTING PROTOCOLS SUMMARY

There are two main categories into which VANET routing protocols divided such as position based and topology based routing protocols [11] [12] [13]. Each routing protocol has its own advantages as well as disadvantages. Following figure 1 is showing this categorization.

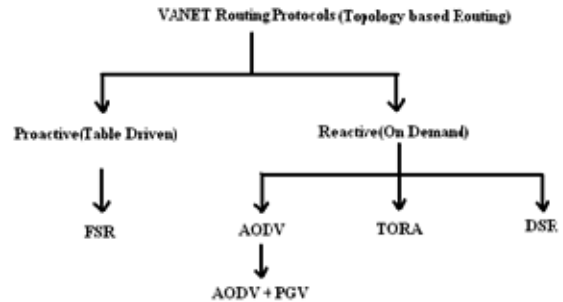


Figure 1: VANET routing protocols categorization

Apart from these basic two categories, the two other categories also presented such as cluster based and broadcast based routing protocols. Below figure 2 is showing comparative analysis of these four categories of routing protocol.

Protocols	Proactive Protocols	Reactive Protocols	Cluster Based Protocols	Broadcast Protocols
Prior Forwarding Method	Wireless Multi Hop Forwarding	Wireless Multi Hop Forwarding	Wireless Multi Hop Forwarding	Wireless Multi Hop Forwarding
Digital Map Requirement	No	No	Yes	No
Virtual Infrastructure Requirement	No	No	Yes	No
Realistic Traffic Flow	Yes	Yes	No	Yes
Recovery Strategy	Yes	Yes		Yes
Scenario	Urban	Urban	Urban	Highway

Figure 2: Comparative Study of VANET routing protocols.

VI. CONCLUSION AND FUTURE WORK

In this paper we have presented the review of VANET new cluster based routing protocol with new mobility models those are recently presented for improvement in routing performance for VANET networks. We discussed the two algorithms which are used for the performance improvement of routing protocol in VANET. In addition to this we also summarized the comparative study of different existing VANET routing protocols with their characteristics. Basically VANET protocols are divided into four common categories such as proactive, reactive, cluster based and broadcast routing protocols. For the future work, we suggest to work on geographical location based routing protocol with aim of improving the throughput as well as energy consumption.

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